## 10-Bit Multiplying D/A Converter

The AD7533 is a monolithic, low cost, high performance, 10-bit accurate, multiplying digital-to-analog converter (DAC), in a 16 pin DIP.

Intersil's thin film resistors on CMOS circuitry provide 10-bit resolution (8-bit accuracy), with TTL/CMOS compatible operation.

The AD7533's accurate four quadrant multiplication, full input protection from damage due to static discharge by clamps to V+ and GND, and very low power dissipation make them very versatile converters.

Low noise audio gain controls, motor speed controls, digitally controlled gain and digital attenuators are a few of the wide range of applications of the AD7533.

## Functional Block Diagram



## Features

- 8-Bit Linearity
- Low Gain and Linearity Temperature Coefficients
- Full Temperature Range Operation
- Static Discharge Input Protection
- TTL/CMOS Compatible
- Supply Range. . . . . . . . . . . . . . . . . . . . . . . . . +5 V to +15 V
- Fast Settling Time at $25^{\circ} \mathrm{C}$

150ns (Max)

- Four Quadrant Multiplication
- AD7533 Direct AD7520 Equivalent


## Pinout



NOTE: Switches shown for digital inputs "High"

## Ordering Information

| PART NUMBER | NUMBER <br> OF BITS | LINEARITY (INL, DNL) | TEMP. RANGE $\left({ }^{\circ} \mathrm{C}\right)$ | PACKAGE | PKG. NO. |
| :--- | :---: | :---: | :---: | :---: | :---: |
| AD7533JN | 10 | $0.2 \%(8-\mathrm{Bit})$ | 0 to 70 | 16 Ld PDIP | E16.3 |


| Absolute Maximum Ratings |  |
| :---: | :---: |
| Supply Voltage (V+ to GND) | +17V |
| $V_{\text {REF }}$ | $\pm 25 \mathrm{~V}$ |
| Digital Input Voltage Range | V+ to GND |
| Output Voltage Compliance | -100 mV to $\mathrm{V}+$ |
| Operating Conditions |  |
| Temperature Range | $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ |

## Thermal Information

| Thermal Resistance (Typical, Note 1) | $\theta_{\mathrm{JA}}\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right)$ |
| :---: | :---: |
| PDIP Package | 90 |
| Maximum Junction Temperature (Plastic Package) | .$^{150}{ }^{\circ} \mathrm{C}$ |
| Maximum Storage Temperature. | C to $150^{\circ} \mathrm{C}$ |
| Maximum Lead Temperature (Soldering 10s) .. | $300^{\circ} \mathrm{C}$ |

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

NOTE:

1. $\theta_{\mathrm{JA}}$ is measured with the component mounted on a low effective thermal conductivity test board in free air. See Tech Brief TB379 for details.

## Electrical Specifications $\quad \mathrm{V}+=+15 \mathrm{~V}, \mathrm{~V}_{\mathrm{REF}}=+10 \mathrm{~V}, \mathrm{~V}_{\mathrm{OUT} 1}=\mathrm{V}_{\mathrm{OUT} 2}=0 \mathrm{~V}$, Unless Otherwise Specified

| PARAMETER |  | TEST CONDITIONS | $\mathrm{T}_{\mathrm{A}} \mathbf{2 5}^{\circ} \mathrm{C}$ |  | TA MIN-MAX |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | MAX | MIN | MAX |  |
| SYSTEM PERFORMANCE |  |  |  |  |  |  |  |
| Resolution |  |  |  | 10 | - | 10 | - | Bits |
| Nonlinearity |  | $-10 \mathrm{~V} \leq \mathrm{V}_{\text {REF }} \leq+10 \mathrm{~V}, \mathrm{~V}_{\text {OUT1 }}=\mathrm{V}_{\text {OUT2 }}=0 \mathrm{~V}($ Notes $2,3,6)$ | - | $\pm 0.2$ | - | $\pm 0.2$ | $\begin{aligned} & \% \text { of } \\ & \text { FSR } \end{aligned}$ |
| Monotonicity |  |  | Guaranteed |  |  |  |  |
| Gain Error |  | All Digital Inputs High (Note 3) | - | $\pm 1.4$ | - | $\pm 1.8$ | $\begin{aligned} & \% \text { of } \\ & \text { FSR } \end{aligned}$ |
| Nonlinearity Tempco |  | $\begin{aligned} & -10 \mathrm{~V} \leq \mathrm{V}_{\mathrm{REF}} \leq+10 \mathrm{~V} \\ & (\text { Notes 3, 4) } \end{aligned}$ | - | $\pm 2$ | - | $\pm 2$ | $\begin{aligned} & \mathrm{ppm} \text { of } \\ & \mathrm{FSR} /{ }^{\circ} \mathrm{C} \end{aligned}$ |
| Gain Error Tempco |  |  | - | $\pm 10$ | - | $\pm 10$ | $\begin{aligned} & \mathrm{ppm} \text { of } \\ & \mathrm{FSR} /{ }^{\circ} \mathrm{C} \end{aligned}$ |
| Output Leakage Current (Either Output) |  | $\mathrm{V}_{\text {OUT1 }}=\mathrm{V}_{\text {OUT2 }}=0$ | - | $\pm 50$ | - | $\pm 200$ | nA |
| DYNAMIC CHARACTERISTICS |  |  |  |  |  |  |  |
| Power Supply Rejection |  | $\mathrm{V}+=14.0 \mathrm{~V}$ to 15.0 V (Note 3) | - | $\pm 0.005$ | - | $\pm 0.008$ | $\begin{gathered} \% \text { of } \\ \text { FSR/\% } \\ \text { of } \Delta V+ \end{gathered}$ |
| Output Current Settling Time |  | To 0.2\% of FSR, $R_{L}=100 \Omega$ (Note 4) | - | 600 | - | 800 | ns |
| Feedthrough Error |  | $V_{\text {REF }}=20 V_{P-P, 200 k H z}$ Sine Wave, All Digital Inputs Low (Note 4) | - | $\pm 0.05$ | - | $\pm 0.1$ | LSB |
| REFERENCE INPUTS |  |  |  |  |  |  |  |
| Input Resistance (Pin 15) |  | All Digital Inputs High lout1 at Ground (Note 4) | 5 | - | 5 | - | k $\Omega$ |
|  |  | - | 20 | - | 20 | $\mathrm{k} \Omega$ |  |
| Temperature Coefficient |  |  | - | -300 | - | -300 | ppm $/{ }^{\circ} \mathrm{C}$ |
| ANALOG OUTPUT |  |  |  |  |  |  |  |
| Output Capacitance | Cout1 |  | All Digital Inputs High (Note 4) | - | 100 | - | 100 | pF |
|  | COUT2 | - |  | 35 | - | 35 | pF |
|  | COUT1 | All Digital Inputs Low (Note 4) | - | 35 | - | 35 | pF |
|  | COUT2 |  | - | 100 | - | 100 | pF |

## Electrical Specifications $\quad \mathrm{V}+=+15 \mathrm{~V}, \mathrm{~V}_{\mathrm{REF}}=+10 \mathrm{~V}, \mathrm{~V}_{\mathrm{OUT} 1}=\mathrm{V}_{\mathrm{OUT} 2}=0 \mathrm{~V}$, Unless Otherwise Specified (Continued)

| PARAMETER | TEST CONDITIONS | TA $\mathbf{2 5}^{\circ} \mathrm{C}$ |  | TA MIN-MAX |  | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | MAX | MIN | MAX |  |
| DIGITAL INPUTS |  |  |  |  |  |  |
| Low State Threshold, $\mathrm{V}_{\text {IL }}$ |  | - | 0.8 | - | 0.8 | V |
| High State Threshold, $\mathrm{V}_{\mathrm{IH}}$ |  | 2.4 | - | 2.4 | - | V |
| Input Current (Low or High), $\mathrm{I}_{\mathrm{IL}}$, $\mathrm{I}_{\mathrm{IH}}$ | $\mathrm{V}_{\mathrm{IN}}=0 \mathrm{~V}$ or +15 V | - | $\pm 1$ | - | $\pm 1$ | $\mu \mathrm{A}$ |
| Input Coding | See Tables 1 through 3 |  | nary/O | et Bina |  |  |
| Input Capacitance | (Note 4) | - | 4 | - | 4 | pF |
| POWER SUPPLY CHARACTERISTICS |  |  |  |  |  |  |
| Power Supply Voltage Range | (Note 6) | +5 to +16 |  |  |  | V |
| I+ | All Digital Inputs High or Low (Excluding Ladder Network) | - | 2 | - | 2.5 | mA |

NOTES:
2. Full Scale Range (FSR) is 10 V for unipolar and $\pm 10 \mathrm{~V}$ for bipolar modes.
3. Using internal feedback resistor, RFEEDBACK.
4. Guaranteed by design or characterization and not production tested.
5. Accuracy not guaranteed unless outputs at ground potential.

6 . Accuracy is tested and guaranteed at $\mathrm{V}+=+15 \mathrm{~V}$, only.

## Definition of Terms

Nonlinearity: Error contributed by deviation of the DAC transfer function from a "best straight line" through the actual plot of transfer function. Normally expressed as a percentage of full scale range or in (sub)multiples of 1 LSB.

Resolution: It is addressing the smallest distinct analog output change that a D/A converter can produce. It is commonly expressed as the number of converter bits. A converter with resolution of $n$ bits can resolve output changes of $2^{-N}$ of the full-scale range, e.g., $2^{-N} V_{\text {REF }}$ for a unipolar conversion. Resolution by no means implies linearity.

Settling Time: Time required for the output of a DAC to settle to within specified error band around its final value (e.g., $1 / 2 \mathrm{LSB}$ ) for a given digital input change, i.e., all digital inputs LOW to HIGH and HIGH to LOW.

Gain Error: The difference between actual and ideal analog output values at full-scale range, i.e., all digital inputs at HIGH state. It is expressed as a percentage of full scale range or in (sub)multiples of 1 LSB.

Feedthrough Error: Error caused by capacitive coupling from $\mathrm{V}_{\text {REF }}$ to $\mathrm{l}_{\text {OUT1 }}$ with all digital inputs LOW.

Output Capacitance: Capacitance from IOUT1, and IOUT2 terminals to ground.

Output Leakage Current: Current which appears on $\mathrm{I}_{\text {OUT1 }}$, terminal when all digital inputs are LOW or on IOUT2 terminal when all digital inputs are HIGH.

For further information on the use of this device, see the following Application Notes:

## Application Notes

| NOTE \# | DESCRIPTION |
| :--- | :--- |
| AN002 | "Principles of Data Acquisition and Conversion" |
| AN018 | "Do's and Don'ts of Applying A/D Converters" |
| AN042 | "Interpretation of Data Conversion Accuracy <br> Specifications" |

## Detailed Description

The AD7533 is a monolithic multiplying D/A converter. A highly stable thin film R-2R resistor ladder network and NMOS SPDT switches form the basis of the converter circuit, CMOS level shifters permit low power TTL/CMOS compatible operation. An external voltage or current reference and an operational amplifier are all that is required for most voltage output applications.

A simplified equivalent circuit of the DAC is shown in the Functional Diagram. The NMOS SPDT switches steer the ladder leg currents between IOUT1 and IOUT2 buses which must be held at ground potential. This configuration maintains a constant current in each ladder leg independent of the input code.

Converter errors are further reduced by using separate metal interconnections between the major bits and the outputs. Use of high threshold switches reduce offset (leakage) errors to a negligible level.

The level shifter circuits are comprised of three inverters with positive feedback from the output of the second to the first,
see Figure 1. This configuration results in TTL/CMOS compatible operation over the full military temperature range. With the ladder SPDT switches driven by the level shifter, each switch is binarily weighted for an ON resistance proportional to the respective ladder leg current. This assures a constant voltage drop across each switch, creating equipotential terminations for the 2 R ladder resistors and high accurate leg currents.


FIGURE 1. CMOS SWITCH

## Typical Applications



NOTES:
7. R1 and R2 used only if gain adjustment is required.
8. CR1 protects AD7533 against negative transients.

FIGURE 2. UNIPOLAR BINARY OPERATION

## Unipolar Binary Operation - (10-Bit DAC)

The circuit configuration for operating the AD7533 in unipolar mode is shown in Figure 2. With positive and negative $\mathrm{V}_{\text {REF }}$ values the circuit is capable of 2-Quadrant multiplication. The "Digital Input Code/Analog Output Value" table for unipolar mode is given in Table 1.

TABLE 1. UNIPOLAR BINARY CODE - AD7533

| DIGITAL INPUT <br> MSB LSB | (NOTE 9) <br> NOMINAL ANALOG OUTPUT |
| :---: | :--- |
| 1111111111 | $-\mathrm{V}_{\text {REF }}\left(\frac{1023}{1024}\right)$ |
| 1000000001 | $-\operatorname{V}_{\text {REF }}\left(\frac{513}{1024}\right)$ |

TABLE 1. UNIPOLAR BINARY CODE - AD7533

| DIGITAL INPUT <br> MSB LSB | (NOTE 9) |
| :---: | :--- |
| 1000000000 | $-\mathrm{V}_{\text {REF }}\left(\frac{512}{1024}\right)=-\frac{\mathrm{V}_{\text {REF }}}{2}$ |
| 0111111111 | $-\mathrm{V}_{\operatorname{REF}}\left(\frac{511}{1024}\right)$ |
| 0000000001 | $-\mathrm{V}_{\operatorname{REF}}\left(\frac{1}{1024}\right)$ |
| 0000000000 | $-\mathrm{V}_{\operatorname{REF}}\left(\frac{0}{1024}\right)=0$ |

NOTES:
9. $\mathrm{V}_{\text {OUT }}$ as shown in Figure 2.
10. Nominal Full Scale for the circuit of Figure 2 is given by:
$F S=-V_{\text {REF }}\left(\frac{1023}{1024}\right)$.
11. Nominal LSB magnitude for the circuit of Figure 2 is given by:
$L S B=V_{\text {REF }}\left(\frac{1}{1024}\right)$.

## Zero Offset Adjustment

1. Connect all digital inputs to GND.
2. Adjust the offset zero adjust trimpot of the output operational amplifier for $0 \mathrm{~V} \pm 1 \mathrm{mV}$ (Max) at $\mathrm{V}_{\text {OUT }}$.

## Gain Adjustment

1. Connect all digital inputs to $\mathrm{V}+$.
2. Monitor $V_{\text {OUT }}$ for a $-V_{\text {REF }}\left(1-1 / 2^{10}\right)$ reading.
3. To increase $\mathrm{V}_{\text {OUT }}$, connect a series resistor, R2, ( $0 \Omega$ to $250 \Omega$ ) in the louT1 amplifier feedback loop.
4. To decrease $\mathrm{V}_{\text {OUT }}$, connect a series resistor, R 1 , $(0 \Omega$ to $250 \Omega$ ) between the reference voltage and the $\mathrm{V}_{\text {REF }}$ terminal.

## Bipolar (Offset Binary) Operation

The circuit configuration for operating the AD7533 in the bipolar mode is given in Figure 3. Using offset binary digital input codes and positive and negative reference voltage values, 4-Quadrant multiplication can be realized. The "Digital Input Code/Analog Output Value" table for bipolar mode is given in Table 2.

A "Logic 1" input at any digital input forces the corresponding ladder switch to steer the bit current to louT1 bus. A "Logic 0" input forces the bit current to IOUT2 bus. For any code the IOUT1 and IOUT2 bus currents are complements of one another. The current amplifier at louT2 changes the polarity of IOUT2 current and the transconductance amplifier at IOUT1 output sums the two currents. This configuration doubles the output range. The difference current resulting at zero offset binary code, (MSB = "Logic 1", all other bits = "Logic 0"), is corrected by using an external resistor, ( $10 \mathrm{M} \Omega$ ), from $\mathrm{V}_{\text {REF }}$ to IOUT2.


FIGURE 3. BIPOLAR OPERATION (4-QUADRANT MULTIPLICATION)

## Offset Adjustment

TABLE 2. UNIPOLAR BINARY CODE - AD7533

| DIGITAL INPUT <br> MSB LSB | (NOTE 2) <br> 1111111111 <br> 1000000001 |
| :--- | :--- |
| 1000000000 | $-\mathrm{V}_{\text {REF }}\left(\frac{511}{512}\right)$ |
| 0111111111 | $+\mathrm{V}_{\text {REF }}\left(\frac{1}{512}\right)$ |
| 0000000001 | $+\mathrm{V}_{\text {REF }}\left(\frac{1}{512}\right)$ |
| 0000000000 | $+\mathrm{V}_{\text {REF }}\left(\frac{511}{512}\right)$ |

## NOTES:

12. $\mathrm{V}_{\text {OUt }}$ as shown in Figure 3.
13. Nominal Full Scale for the circuit of Figure 3 is given by:
$F S R=V_{\text {REF }}\left(\frac{1023}{512}\right)$.
14. Nominal LSB magnitude for the circuit of Figure 3 is given by:
$L S B=V_{\text {REF }}\left(\frac{1}{512}\right)$.
15. Adjust $\mathrm{V}_{\mathrm{REF}}$ to approximately +10 V .
16. Connect all digital inputs to "Logic 1 ".
17. Adjust IOUT2 amplifier offset adjust trimpot for $0 \mathrm{~V} \pm 1 \mathrm{mV}$ at IOUT2 amplifier output.
18. Connect MSB (Bit 1) to "Logic 1" and all other bits to "Logic 0".
19. Adjust IOUT1 amplifier offset adjust trimpot for $0 \mathrm{~V} \pm 1 \mathrm{mV}$ at VOUT.

## Gain Adjustment

1. Connect all digital inputs to $\mathrm{V}+$.
2. Monitor $\mathrm{V}_{\text {OUT }}$ for $a-\mathrm{V}_{\text {REF }}\left(1-2^{-9}\right)$ volts reading.
3. To increase $\mathrm{V}_{\text {OUT }}$, connect a series resistor (R2) of up to $250 \Omega$ between $V_{\text {OUT }}$ and $R_{\text {FEEDBACK }}$.
4. To decrease $\mathrm{V}_{\text {OUT }}$, connect a series resistor (R1) of up to $250 \Omega$ between the reference voltage and the $\mathrm{V}_{\text {REF }}$ terminal.


FIGURE 4. 10-BIT AND SIGN MULTIPLYING DAC


FIGURE 5. PROGRAMMABLE FUNCTION GENERATOR

$V_{\text {OUT }}=-V_{\text {IN/D }}$
Where:
$D=\frac{\text { Bit } 1}{2^{1}}+\frac{\text { Bit } 2}{2^{2}}+\ldots \frac{\text { Bit } 8}{2^{2}}$
$\left(0 \leq \mathrm{D} \leq \frac{255}{256}\right)$
FIGURE 6. DIVIDER (DIGITALLY CONTROLLED GAIN)

$V_{\text {OUT }}=V_{\text {REF }}\left[\left(\frac{R_{2}}{R_{1}+R_{2}}\right)-\left(\frac{R_{1} D}{R_{1}+R_{2}}\right)\right]$
Where $D=\frac{\text { Bit } 1}{2^{1}}+\frac{\text { Bit } 2}{2^{2}}+\ldots \frac{\text { Bit } 8}{2^{8}}$
( $0 \leq \mathrm{D} \leq \frac{255}{256}$ )
FIGURE 7. MODIFIED SCALE FACTOR AND OFFSET

## Die Characteristics

DIE DIMENSIONS
101 mils $\times 103$ mils $(2565 \mu \mathrm{~m} \times 2616 \mu \mathrm{~m})$
METALLIZATION
Type: Pure Aluminum
Thickness: $10 \pm 1 \mathrm{k} \AA$

## PASSIVATION

Type: PSG/Nitride
PSG: $7 \pm 1.4 \mathrm{k} \AA$
Nitride: $8 \pm 1.2 \mathrm{k} \AA$
PROCESS
CMOS Metal Gate

Metallization Mask Layout


## Dual-In-Line Plastic Packages (PDIP)


-B-


NOTES:

1. Controlling Dimensions: $\operatorname{INCH}$. In case of conflict between English and Metric dimensions, the inch dimensions control.
2. Dimensioning and tolerancing per ANSI Y14.5M-1982.
3. Symbols are defined in the "MO Series Symbol List" in Section 2.2 of Publication No. 95.
4. Dimensions $\mathrm{A}, \mathrm{A} 1$ and L are measured with the package seated in JEDEC seating plane gauge GS-3.
5. D, D1, and E1 dimensions do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.010 inch ( 0.25 mm ).
6. $E$ and $\mathrm{e}_{\mathrm{A}}$ are measured with the leads constrained to be perpendicular to datum $-\mathrm{C}-$.
7. $e_{B}$ and $e_{C}$ are measured at the lead tips with the leads unconstrained. $\mathrm{e}_{\mathrm{C}}$ must be zero or greater.
8. B1 maximum dimensions do not include dambar protrusions. Dambar protrusions shall not exceed 0.010 inch $(0.25 \mathrm{~mm})$.
9. N is the maximum number of terminal positions.
10. Corner leads ( $1, \mathrm{~N}, \mathrm{~N} / 2$ and $\mathrm{N} / 2+1$ ) for E8.3, E16.3, E18.3, E28.3, E42.6 will have a B1 dimension of $0.030-0.045$ inch ( $0.76-1.14 \mathrm{~mm}$ ).

E16.3 (JEDEC MS-001-BB ISSUE D) 16 LEAD DUAL-IN-LINE PLASTIC PACKAGE

| SYMBOL | INCHES |  | MILLIMETERS |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |  |
| A | - | 0.210 | - | 5.33 | 4 |
| A1 | 0.015 | - | 0.39 | - | 4 |
| A2 | 0.115 | 0.195 | 2.93 | 4.95 | - |
| B | 0.014 | 0.022 | 0.356 | 0.558 | - |
| B1 | 0.045 | 0.070 | 1.15 | 1.77 | 8,10 |
| C | 0.008 | 0.014 | 0.204 | 0.355 | - |
| D | 0.735 | 0.775 | 18.66 | 19.68 | 5 |
| D1 | 0.005 | - | 0.13 | - | 5 |
| E | 0.300 | 0.325 | 7.62 | 8.25 | 6 |
| E1 | 0.240 | 0.280 | 6.10 | 7.11 | 5 |
| e | 0.100 BSC | $2.54 ~ B S C$ | - |  |  |
| $e_{A}$ | $0.300 ~ B S C$ | $7.62 ~ B S C$ | 6 |  |  |
| $e_{B}$ | - | 0.430 | - | 10.92 | 7 |
| L | 0.115 | 0.150 | 2.93 | 3.81 | 4 |
| N | 16 |  | 16 |  | 9 |

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